

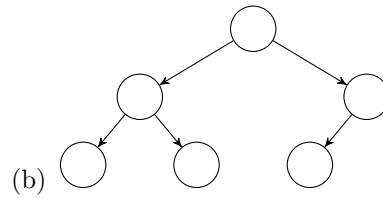
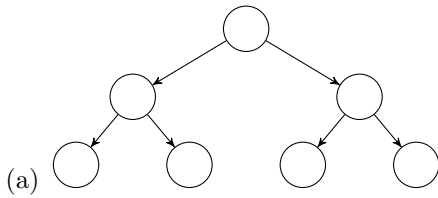
## Tree Algorithms

### 1. (Fun with red-black trees) (Difficulty: Easy)

Recall the five rules for red-black trees:

- Every vertex is colored **red** or **black**.
- The root vertex is a **black** vertex.
- A NIL child is a **black** vertex.
- The child of a **red** vertex must be a **black** vertex.
- For all vertices  $v$ , all paths from  $v$  to its NIL descendants have the same number of **black** vertices.

Consider the following binary search trees. Which of the following vertices must be black in **any** valid red-black coloring?



## 2. (Randomly built BST's) (Difficulty: Hard)

Here, we prove that the average depth of a vertex in a randomly built binary search tree with  $n$  vertices is  $O(\log(n))$ . A **randomly built binary search tree** with  $n$  vertices is one that arises from inserting the  $n$  keys in random order into an initially empty tree, where each of the  $n!$  permutations of the input keys is equally likely.

Let  $d(x, T)$  be the depth of vertex  $x$  in a binary tree  $T$  (the depth of the root is 0). Then, the average depth of a vertex in a binary tree  $T$  with  $n$  vertices is

$$\frac{1}{n} \sum_{x \in T} d(x, T)$$

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- (a) Let the *total path length*  $P(T)$  of a binary tree  $T$  be defined as the sum of the depths of all vertices in  $T$ , so the average depth of a vertex in  $T$  with  $n$  vertices is equal to  $\frac{1}{n}P(T)$ . Show that  $P(T) = P(T_L) + P(T_R) + n - 1$ , where  $T_L$  and  $T_R$  are the left and right subtrees of  $T$ , respectively. **[We are expecting: A rigorous mathematical proof.]**

- (b) Let  $P(n)$  be the expected total path length of a randomly built binary search tree with  $n$  vertices. Show that

$$P(n) = \frac{1}{n} \sum_{i=0}^{n-1} (P(i) + P(n-i-1) + n-1)$$

[We are expecting: A rigorous mathematical proof.]

- (c) Show that  $P(n) = O(n \log(n))$ . Hint: You might want to revisit quicksort.

[We are expecting: A short English justification.]

- (d) Design a sorting algorithm based on randomly building a binary search tree. Show that its expected runtime is  $O(n \log(n))$ . Assume that a random permutation of  $n$  keys can be generated in  $O(n)$ -time.

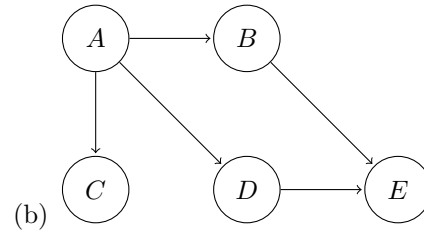
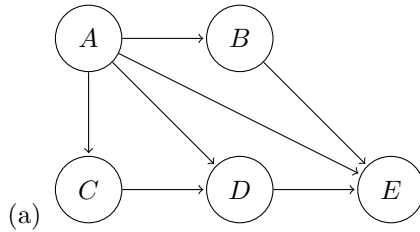
[We are expecting: An English description of the algorithm and a brief justification for its runtime.]

# Graph Algorithms

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## 1. (Fun with graphs) (Difficulty: Easy)

For each of the following graphs, assuming a vertex's neighbors will be visited in alphabetical order, what will be the ordering of end times from lowest to highest for **dfs** and order of visited times for **bfs**, starting from *A*.



## 2. (DFS) (Difficulty: Easy)

Implement **dfs** without using recursion, still with runtime  $O(|V| + |E|)$ .

[We are expecting: An pseudocode of the algorithm and a brief justification for its runtime.]

3. **(Robotic reduction) (Difficulty: Medium)**

Consider a robot that can take steps of  $k$  distinct lengths  $s_1, s_2, \dots, s_k \in \mathbb{Z}$  in feet. The robot starts at position  $p_0$  on a circular track with circumference length  $T \in \mathbb{N}$  in feet and it starts walking counter-clockwise around the track to calibrate itself. It takes one step for each of the lengths  $s_1, s_2, \dots, s_k$ , bringing it to position  $p_1$ .

Describe an  $O(T + kT)$ -time algorithm that finds the fewest number of steps that the robot needs to take to get back to position  $p_0$ , assuming the robot can't turn around (all steps must be taken in the counter-clockwise direction).

**[We are expecting: An English description of the algorithm and a brief justification for its runtime.]**

#### 4. (2SAT-SCC) (Difficulty: Hard)

In 2SAT, you have a set of boolean clauses, each containing two variables. Your goal is to set all of these clauses to true, or report that doing so is not possible. For example,

$$(x_1 \vee x_2) \wedge (\bar{x}_1 \vee x_3) \wedge (\bar{x}_2 \vee \bar{x}_3)$$

can be satisfied by setting  $x_1$  and  $x_3$  to true and  $x_2$  to false.

- (a) First, it helps to decompose clauses into their implications i.e. a clause represented by  $a \vee b$  would be represented by  $\bar{a} \rightarrow b$  and  $\bar{b} \rightarrow a$ . What are the implications in the clauses above?

**[We are expecting: A list of implications.]**

- (b) To solve this problem with a graph algorithm, first built a graph by creating two vertices for each variable  $x$ :  $x$  and  $\bar{x}$ . Then, add directed edges based in the implications from each clause. What is the graphical representation of the above boolean clauses?

**[We are expecting: A directed graph.]**

- (c) What do SCC's in these 2SAT graphs represent? What if  $x$  and  $\bar{x}$  were part of the same SCC?

**[We are expecting: Answers to the questions.]**

- (d) Assume we have a sink SCC  $C$  from the graph, and that no variable and its negation both appear inside of  $C$ . If  $C$  has vertices of the form  $a, b, \dots, z$ , what corresponding component do we know must exist in the graph? Is there an edge between these two components?

**[We are expecting: Answers to the questions.]**

- (e) Given this graph and the properties above, develop an algorithm to solve 2SAT.

**[We are expecting: An English description of the algorithm.]**